

NR60 Encoder Sample Program – READ ME

NOTE: This NR60 Encoder Sample Program was created to communicate with the NR60-M28 (multi-turn 28-bit encoder) but it can be also used with either the NR60-S16 (single-turn 16-bit) or with the NR60-M30 (multi-turn 30-bit) encoders. Standard Telegram 83 (ST83) is used in this example for cyclic data exchange between the NR60 encoder and a SIEMENS controller. It is also possible to use other supported telegrams, such as ST81, ST82, ST84, and AMCI T860, and this is explained in more detail in the following text.

This NR60 encoder sample program is written assuming that you are already familiar with the NR60 encoder and are able to add it to your network. Please refer to the AMCI NR60 User Manual, which can be found on AMCI's web site, if you have any questions related to the installation.

CYCLIC DATA EXCHANGE

For cyclic data exchange, the NR60 encoder uses standard telegrams that cyclically update the I/O area of the SIMATIC CPU. The ST83 telegram cyclically updates the I/O input area with 16 bytes of data that includes status words, position, and velocity.

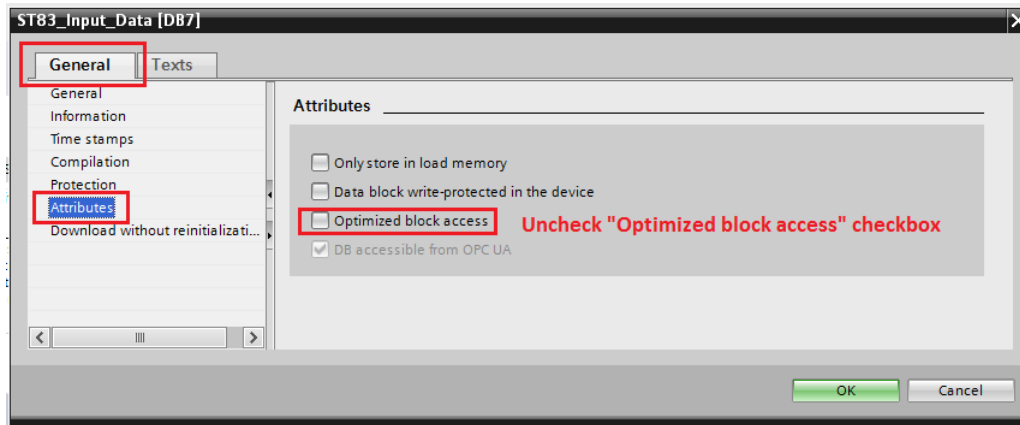
A **DPRD_DAT** instruction is used to read data from the I/O input area, store it in a dedicated data block, and ensures that consistent data from the NR60 device are all from the same bus cycle. This instruction has 3 parameters that need to be assigned:

- The **LADDR** parameter selects the PROFINET I/O module from which data will be read. As shown in the following figure, to find an available address, open either the **Default tag table** or **Show all tags** and select the **System constants** tab.
- The **RECORD** parameter defines the target **Data Block (DB)**, which will contain the NR60's data that is being read by this instruction.
- The **RET_VAL** parameter will contain an error code if an error occurs while the instruction is being executed.

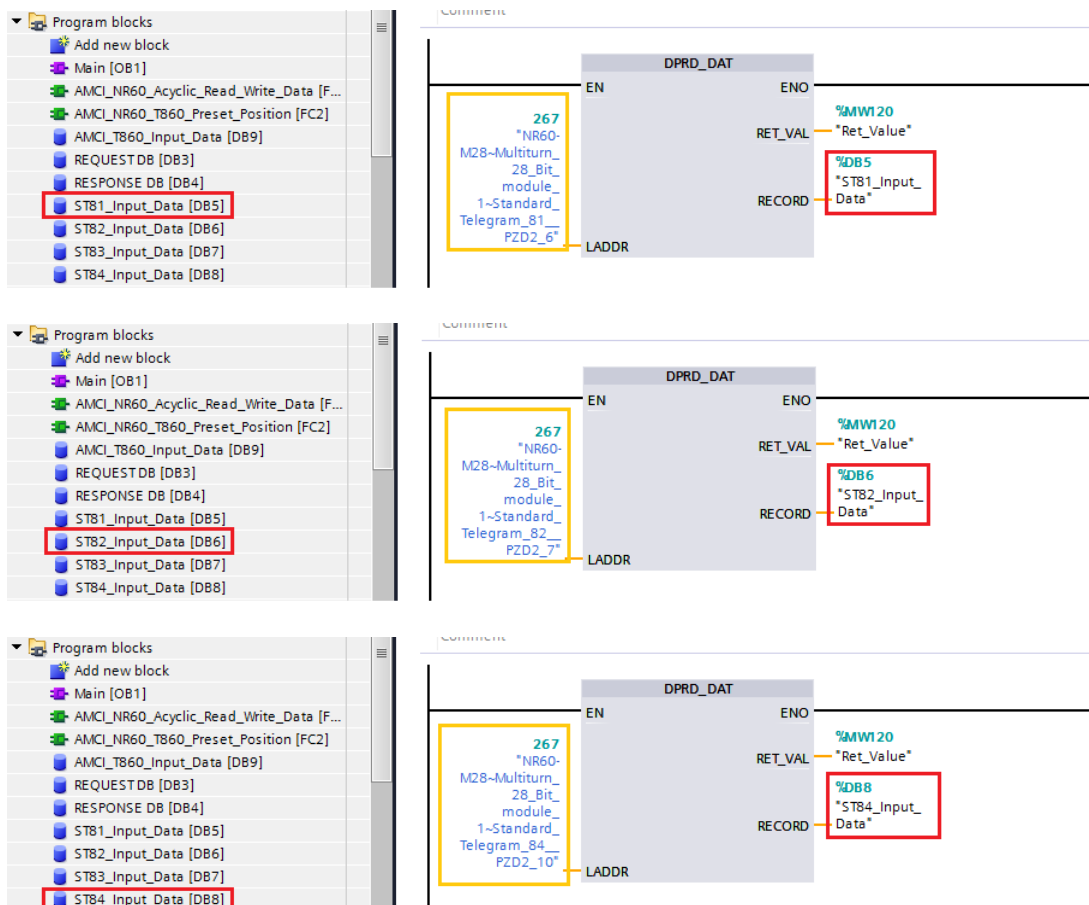
The screenshot displays the Siemens SIMATIC Manager interface. The top part shows the Ladder Logic (LAD) editor with a **DPRD_DAT** instruction. The **LADDR** parameter is set to **267**, which is linked to the tag ***NR60-M28-Multiturn_28_Bit_module_1-Standard_Telegram_83_PZD2_8**. The **RECORD** parameter is set to **%DB7**, linked to the tag ***ST83_Input_Data**. The **RET_VAL** parameter is set to **%MW120**, linked to the tag ***Ret_Value**. The bottom part shows the **Default tag table** for the **System constants** tab. The table lists various tags and their data types and values.

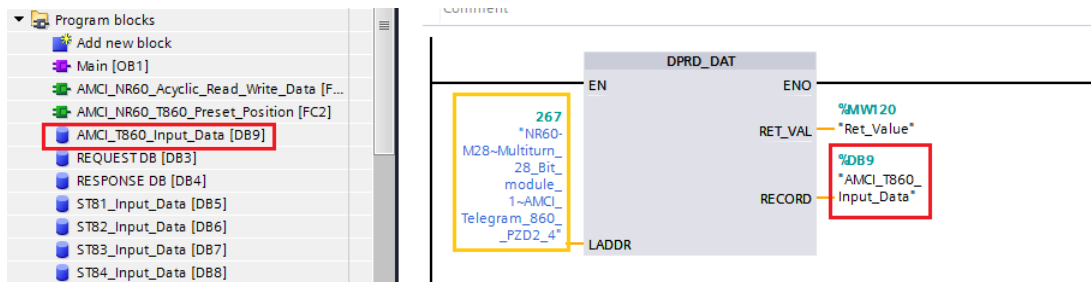
Name	Data type	Value	Comme...
NR60-M28-Proxy	Hw_SubModule	258	
NR60-M28-IODevice	Hw_Device	263	
NR60-M28-PN-IO	Hw_Interface	259	
NR60-M28-PN-IO-Port_1	Hw_Interface	260	
NR60-M28-PN-IO-Port_2	Hw_Interface	261	
NR60-M28-Head	Hw_SubModule	262	
NR60-M28-Multiturn_28_Bit_module_1	Hw_SubModule	264	
NR60-M28-Multiturn_28_Bit_module_1_1	Hw_SubModule	266	
NR60-M28-Multiturn_28_Bit_module_1-Standard_Telegram_83_PZD2_8	Hw_SubModule	267	

The **“Optimized block access”** attribute of the target data block (*ST83_Input_Data* [DB7] in this case) must be unchecked for the DPRD_DAT instruction to work correctly. To verify the status of this attribute, right click on the selected data block and, from the pop-up menu, choose **Properties ...** As shown in the following image, in the **Properties** window under the **General** tab, select **Attributes**, and verify that the **“Optimized block access”** is unchecked.



If you want to create a program with a different standard telegram, replace the existing ST83 with the one of your choice under the **Device view** tab and modify the DPRD_DAT instruction to match new standard telegram. Data blocks for each standard telegram already exist:





Standard Telegram ST83, like all other available telegrams, also cyclically updates the I/O output area, but with only 4 bytes of data. For this reason there is no need to use DPWR_DAT instruction and, as shown in the **Watch and force table** file, the data from the controller will be sent directly to the I/O output area that is used in the sample program:

NR60_Sample_Program_CP_V15.1 ▶ PLC_1 [CPU 1516-3 PN/DP] ▶ Watch and force tables ▶ Standard Telegram 83

	Name	Address	Display fo...	Monitor value	Modify value	
1						
2	// If the Compatibility Mode, in your Configuration, is not enabled, then set this bit to let your controller (PLC) to assume control.					
3	*STW2_ENC: Control from PLC*	%Q0.2	Bool		TRUE	<input type="checkbox"/>
4						<input type="checkbox"/>
5	// Set or reset the following bits from the Sensor Control Word to perform any of the given functions.					
6	*G1_STW: Home position mode*	%Q2.3	Bool		FALSE	<input type="checkbox"/>
7	*G1_STW: Request set/shift of home position*	%Q2.4	Bool		FALSE	<input type="checkbox"/>
8	*G1_STW: Request absolute value cyclically*	%Q2.5	Bool		FALSE	<input type="checkbox"/>
9	*G1_STW: Activate parking sensor*	%Q2.6	Bool		FALSE	<input type="checkbox"/>
10	*G1_STW: Acknowledging a sensor error*	%Q2.7	Bool		FALSE	<input type="checkbox"/>

ACYCLIC DATA EXCHANGE

Acyclic data exchange writes parameters to or reads parameters from the NR60 encoder. To accomplish this task, two instructions are used: WRREC and RDREC. In addition to these two instructions, two data blocks must also be created. Note that the **“Optimized block access”** attribute for both data blocks must be unchecked in the same way that it was unchecked in the **Cyclic Data Exchange** section above. The first data block, named REQUEST DB, is used to hold the required request data that is sent to the NR60 encoder.

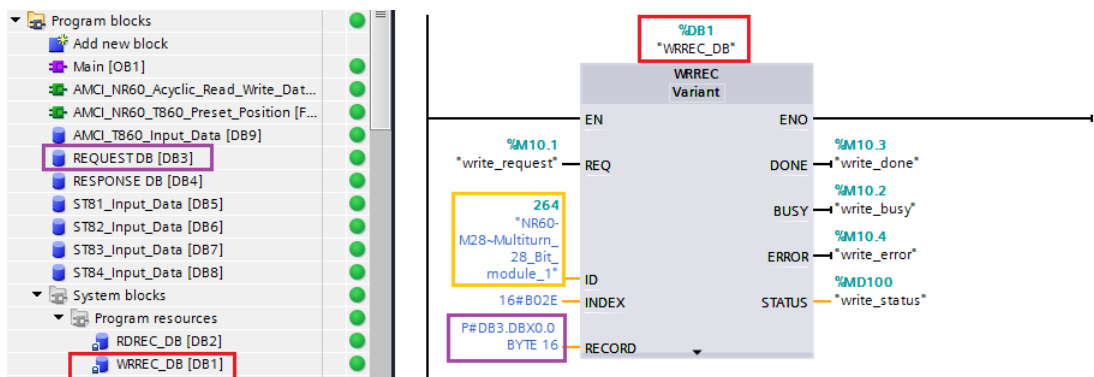
NR60_Sample_Program_CP_V15.1 ▶ PLC_1 [CPU 1516-3 PN/DP] ▶ Program blocks ▶ REQUEST DB [DB3]

	Name	Data type	Offset	Start value	Retain	Accessible f...	Writa...	Visible in ...	Setpoint
1	Static								
2	Request_Reference	Byte	0.0	16#1	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>
3	Request_ID	Byte	1.0	16#2	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>
4	DO_ID	Byte	2.0	16#0	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>
5	No_of_Parameters	Byte	3.0	16#1	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>
6	Attribute	Byte	4.0	16#10	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>
7	No_of_Elements	Byte	5.0	16#1	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>
8	Parameter_Index	Word	6.0	16#FDE8	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>
9	Subindex	Word	8.0	16#0	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>
10	Format	Byte	10.0	16#43	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>
11	No_of_Values	Byte	11.0	16#1	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>
12	Value	DWord	12.0	16#0	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>

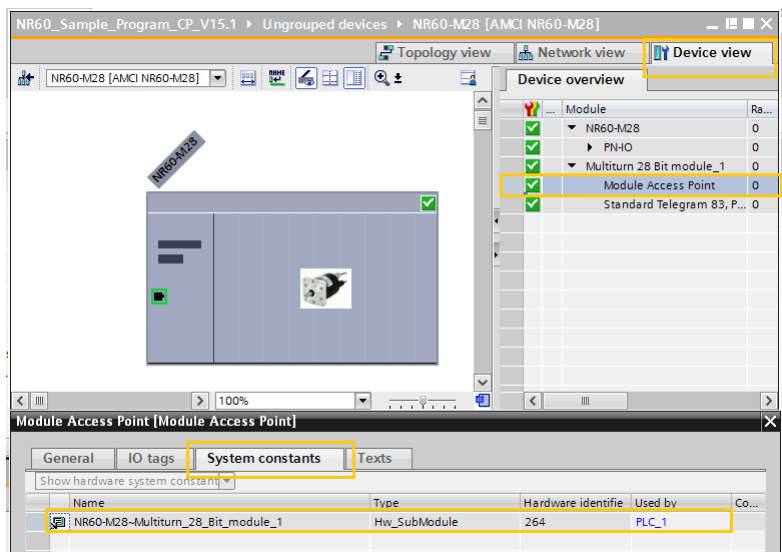
The second one, named RESPONSE DB, is used to hold the response data coming from the NR60 encoder, after the read or write request is completed.

	Name	Data type	Offset	Start value	Retain	Accessible f...	Writa...	Visible in ...	Setpoint
1	Static								
2	Request_Reference	Byte	0.0	16#0		<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	
3	Response_ID	Byte	1.0	16#0		<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	
4	DO_ID	Byte	2.0	16#0		<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	
5	No_of_Parameters	Byte	3.0	16#0		<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	
6	Format	Byte	4.0	16#0		<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	
7	No_of_Values	Byte	5.0	16#0		<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	
8	Value	DWord	6.0	16#0		<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	

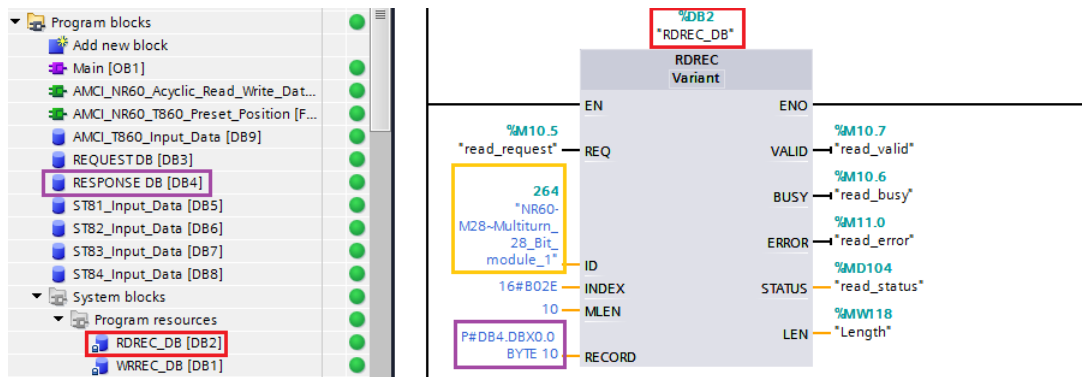
The WRREC instruction sends the read or write request to the NR60 encoder. As you can see, there is a System block (WRREC_DB) that is automatically assigned to the instruction when it is inserted in the ladder logic. The **RECORD** input is pointing to the REQUEST DB (DB3) that is 16 bytes long.



The **ID** input is a Hardware ID and, as shown in the following image, it can be found under the **Device view** tab, **Module Access Point** properties, and finally under the **System constants** tab.



The RDREC instruction receives requested data from the NR60 encoder. There is also a System block (RDREC_DB) that is automatically assigned to the instruction. The **RECORD** input is pointing to the RESPONSE DB (DB4) that is 10 bytes long. The **ID** input is a Hardware ID that is the same as it was for the WRREC instruction.



This sample program uses the NR60's default configuration. To change any of the configuration parameters, go OFF line, make the changes to the parameters, save the changes, compile the program, and download it to the controller. Go ON line.

